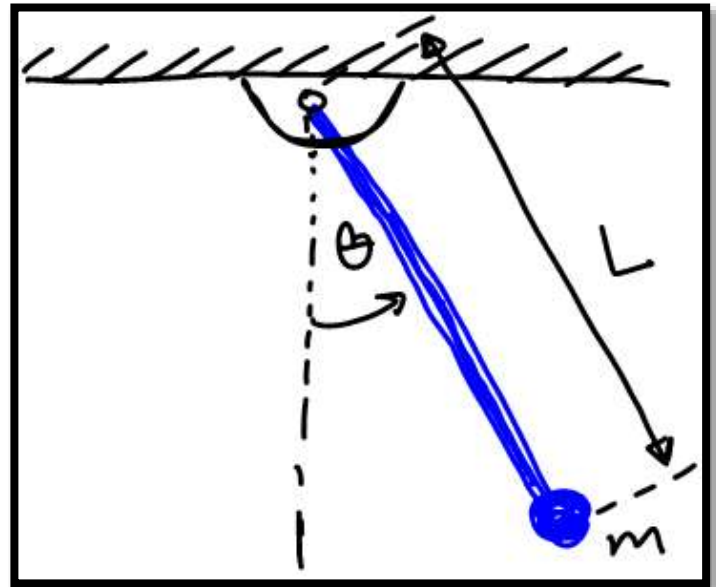


|                                                                      |                                                                                   |                                                                       |                        |
|----------------------------------------------------------------------|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------|------------------------|
| Mansoura University                                                  |  | Computer Engineering and Control Syst. Dept.<br>Total Marks: 90 Marks | Faculty of Engineering |
| Course Title: <b>Control Engineering 1</b>                           |                                                                                   | Course Code: <b>CSE 3116</b>                                          |                        |
| Date: 11 Jan. 2015                                                   |                                                                                   | Allowed time: 3 hr.                                                   | No. of Pages: (02)     |
| Remarks: (Answer the following questions... assume any missing data) |                                                                                   |                                                                       |                        |

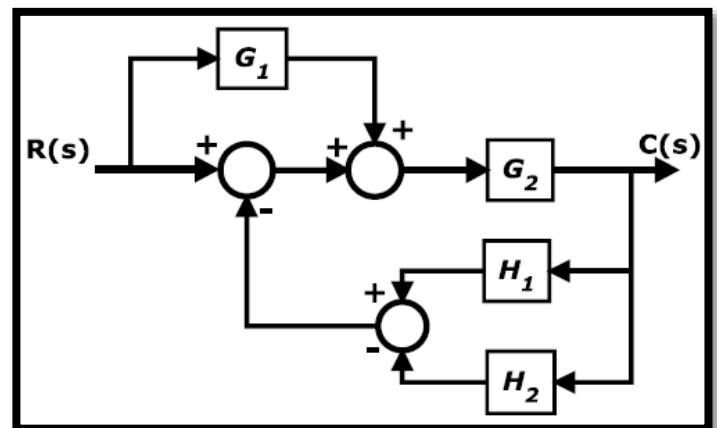
### Question No. (1) (15 Marks)

For the simple pendulum shown, where  $L = 0.5 \text{ m}$ ,  $m = 1 \text{ kg}$ , and  $g = 9.8 \text{ m/s}^2$ . Create an **.m** file to **plot the linear response** of the simple pendulum when the initial angle of the pendulum is  $\theta(0) = 30^\circ$



### Question No. (2) (15 Marks)

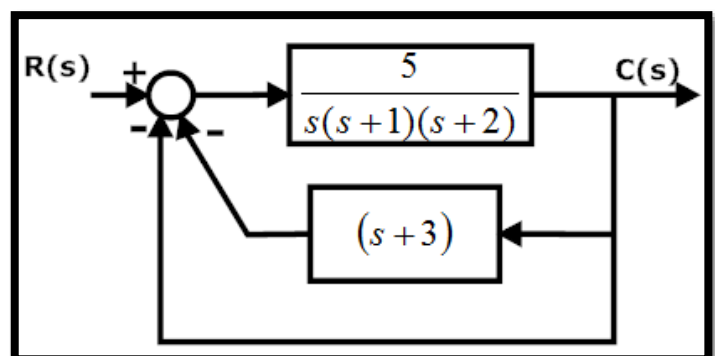
Find the closed-loop transfer function  $\frac{C(s)}{R(s)}$  for the system shown below



### Question No. (3) (15 Marks)

For the system shown in figure

- Find  $K_p$ ,  $K_v$ , and  $K_a$
- Find the steady-state error for an input of  $50u(t)$
- Under what conditions your answer in point (b) is valid
- State the system type



#### Question No. (4) (15 Marks)

Obtain the unit-impulse response of a unity feedback system whose open-loop transfer function is  $G(s) = \frac{2s+10}{s^2}$

#### Question No. (5) (15 Marks)

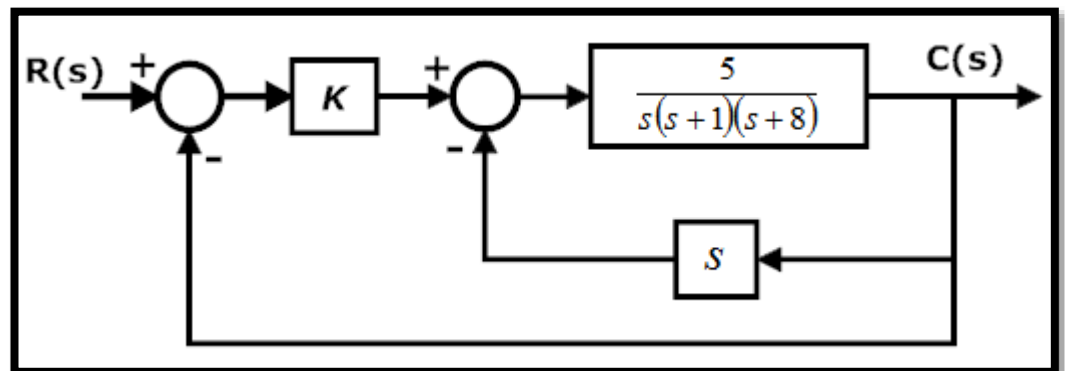
Consider the closed-loop system given by

$$\frac{C(s)}{R(s)} = \frac{\omega_n}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

Determine the values of  $\zeta$  and  $\omega_n$  so that the system responds to a step input with approximately 5% overshoot and with a settling time (**2% criteria**) of 2 sec.

#### Question No. (6) (15 Marks)

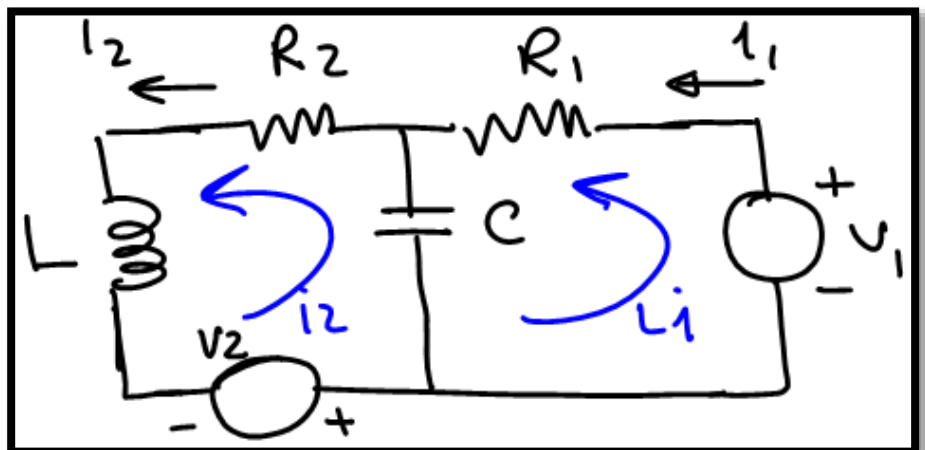
A model of a ship's heading control loop is shown in the figure below. Find the range of  $K$  that will keep the system stable



#### Question No. (7) (15 Marks)

Sketch the block diagram for the electrical circuit show next, and then determine

$$\left. \frac{I_2}{V_1} \right|_{V_2=0}$$



Best wishes

Dr. Mostafa Elhosseini

Dr. Amira Yassien Haikel