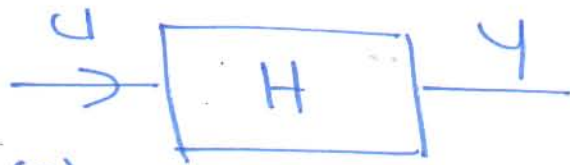


System Response

Once the transfer function has been determined by any of the available methods, we can start to analyze the response



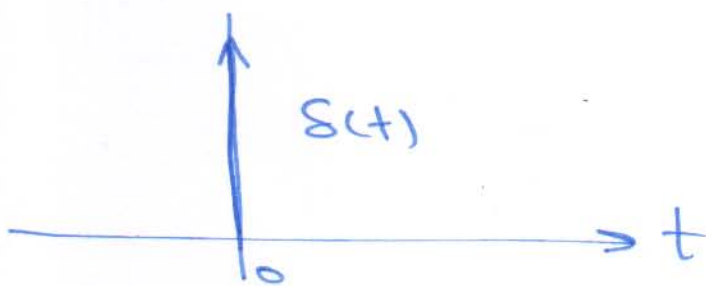
$$H(s) = T.f = \frac{b(s)}{a(s)}$$

Pole: s -value at which $a(s) = 0$

Zero: s -value at which $b(s) = 0$

Hint

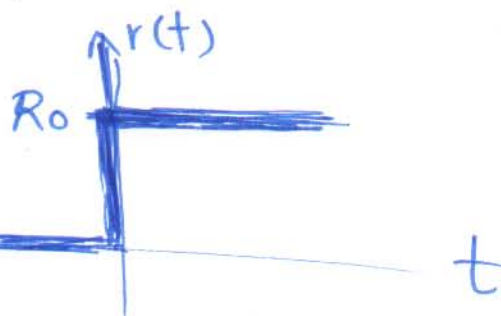
① impulse input



$$\delta(t) = 0 \quad t \neq 0$$
$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$\delta(s) = 1$$

② Step input

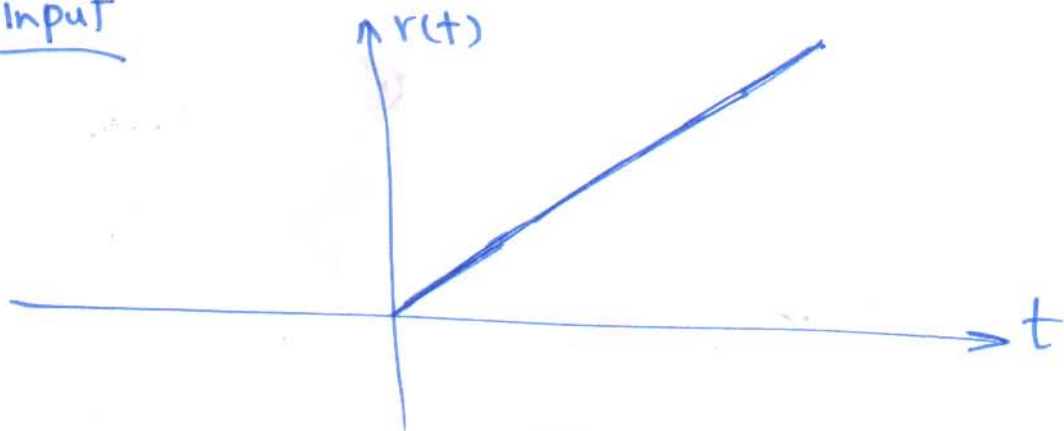


$$r(t) = 0 \quad t < 0$$

$$r(t) = R_0 \quad t \geq 0$$

$$R(s) = \frac{R_0}{s}$$

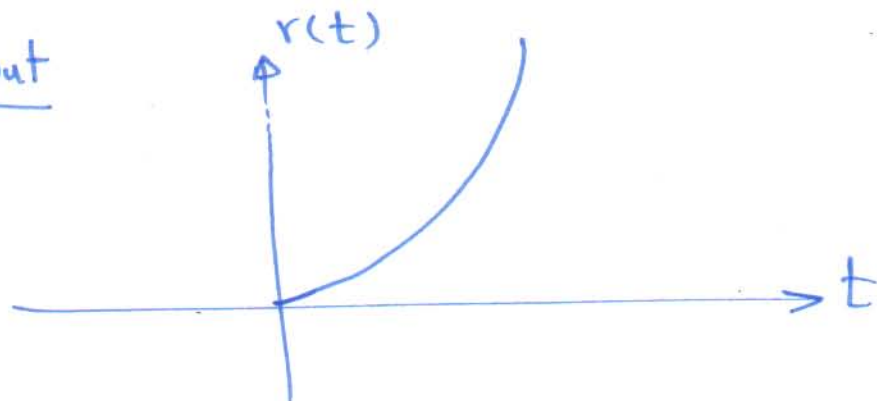
Ramp input



$$r(t) = \begin{cases} At & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$R(s) = \frac{A}{s^2}$$

Parabolic input



$$r(t) = \begin{cases} At^2 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$R(s) = \frac{2A}{s^3}$$

impulse response = natural freq.

Ex

$$T.f = H(s) = \frac{1}{s + \sigma}$$

$$\text{impulse response} = h(t) = e^{-\sigma t}$$

$\sigma > 0 \Rightarrow$ pole located at $s < 0$
 $\Rightarrow$ exponential decays
 $\Rightarrow$ impulse response is stable

$\sigma < 0 \Rightarrow$ pole is right of the origin
 $\Rightarrow$ exponential term grows with time
 $\Rightarrow$ impulse response is unstable

In general

the shapes of the components of the natural responses are determined by the locations of the poles of the t.f

- pole at -2 is faster than the pole at -1
- poles farther to the left in the s-plane are associated with natural signal that decays faster than those associated with poles closer to I-A

Impulse using matlab

• (Ex)

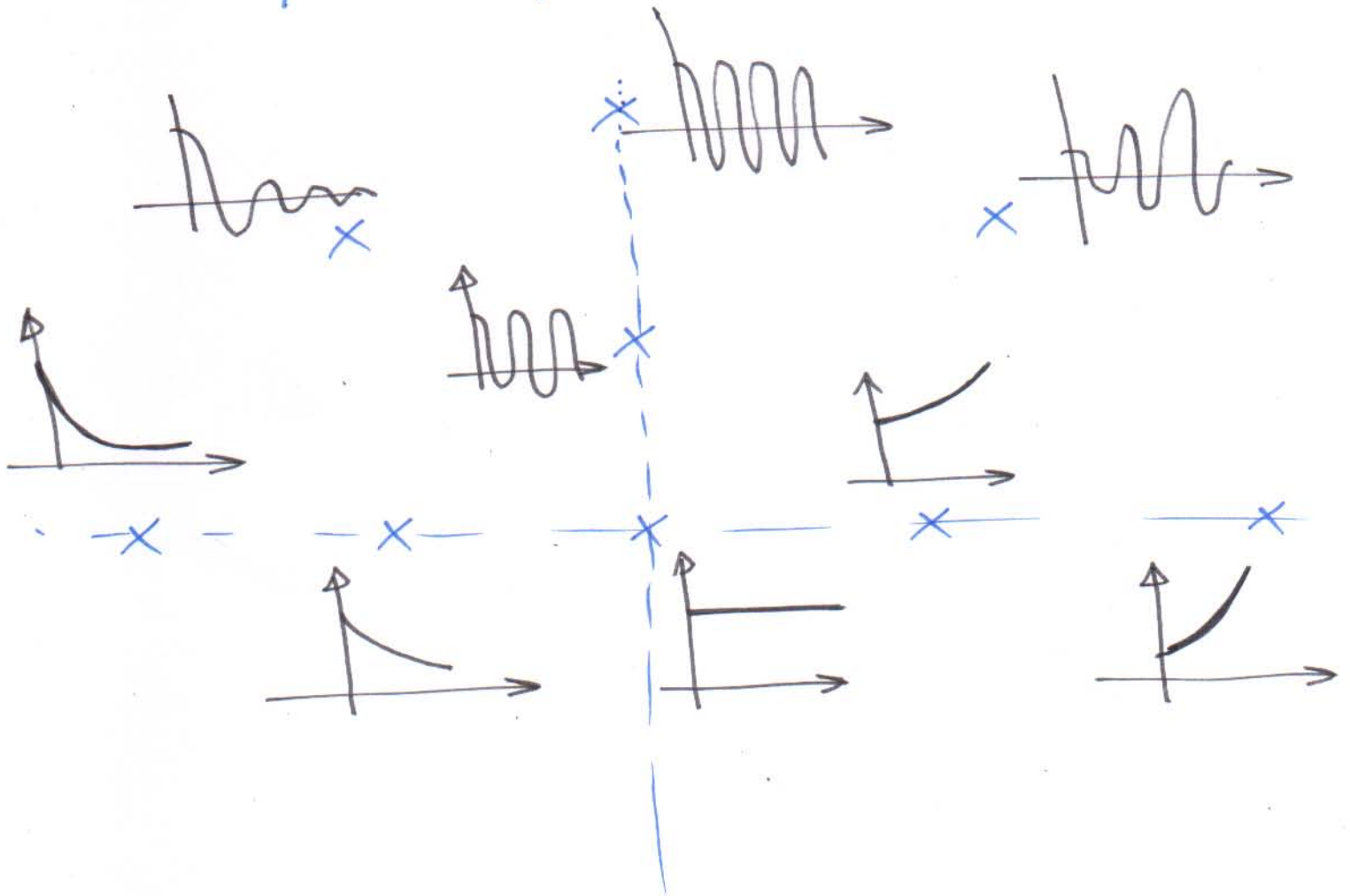
$$H(s) = \frac{2s+1}{s^2+3s+2}$$

>> a = [2 1];

>> b = [1 3 2];

>> sys = tf(a,b);

>> impulse(sys);



Complex poles can be defined as

$$s = -\sigma \pm j\omega_d$$

Since complex poles come in conjugate pairs, then the denominator will be

$$\begin{aligned} a(s) &= (s + \sigma - j\omega_d)(s + \sigma + j\omega_d) \\ &= (s + \sigma)^2 + \omega_d^2 \\ &= s^2 + 2\sigma s + \sigma^2 + \omega_d^2 \end{aligned}$$

when finding the T-f, we typically write the result in rational form

$$\therefore H(s) = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}$$

by comparing $a(s)$ with the denominator of $H(s)$

$$\therefore \sigma = \xi\omega_n$$

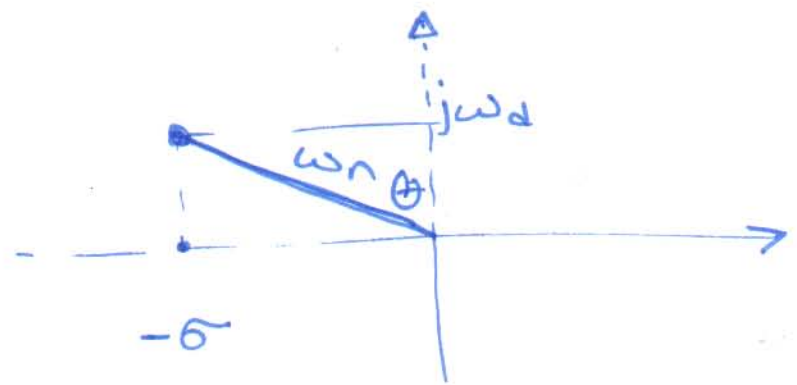
$$\omega_d = \omega_n \sqrt{1 - \xi^2}$$

ξ : damping ratio

ω_d : damped natural freq.

$$\therefore \sigma^2 + \omega_d^2 = \omega_n^2$$

$\therefore$ The bold line $= \omega_n$



$$\sin \theta = \frac{\sigma}{\omega_n}$$

$$\sin \theta = \frac{\xi \omega_n}{\omega_n}$$

$$\therefore \theta = \sin^{-1} \xi$$

if $\xi = 0 \Rightarrow \theta = 0$, we have no damping

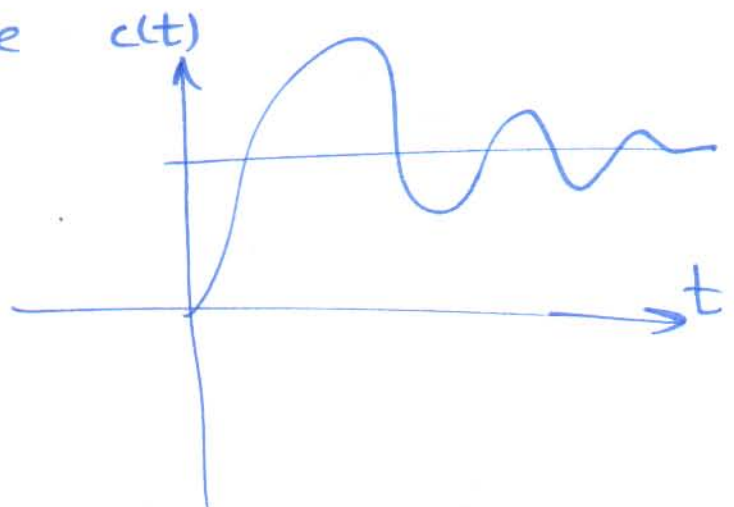
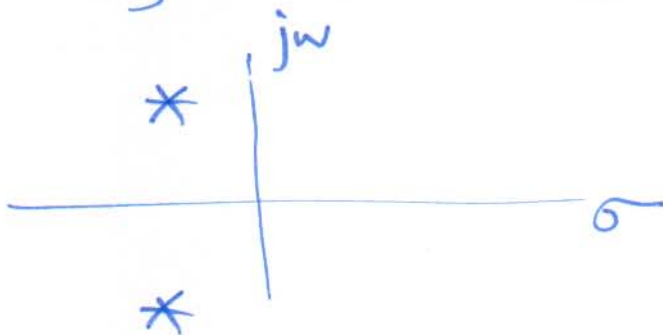
$\hookrightarrow \omega_d = \omega_n$ at $\xi = 0$

$\therefore \omega_d =$ damped natural freq.

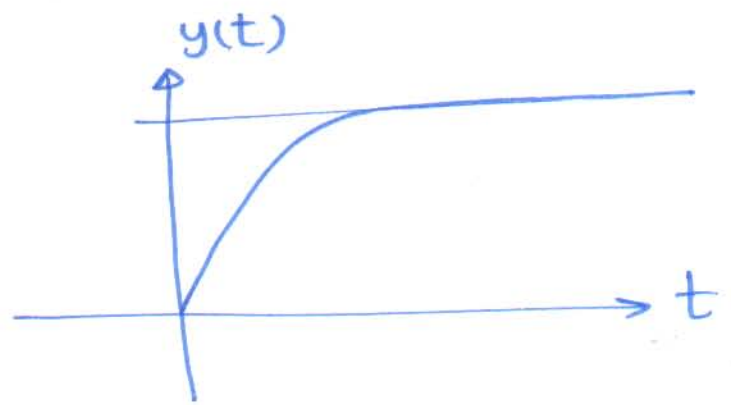
Note

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}$$

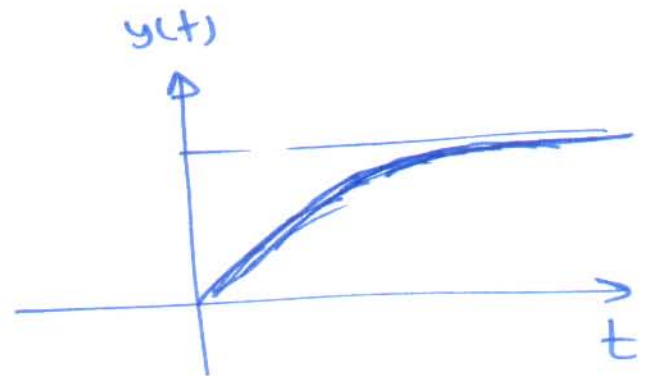
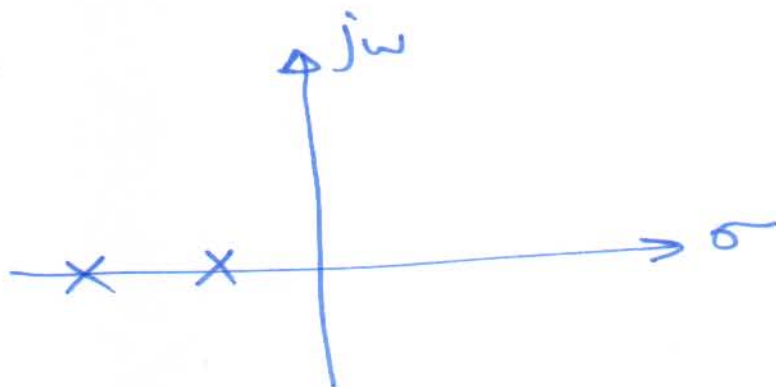
$0 < \xi < 1 \Rightarrow$ underdamped case



$\zeta = 1 \Rightarrow$ critically damped

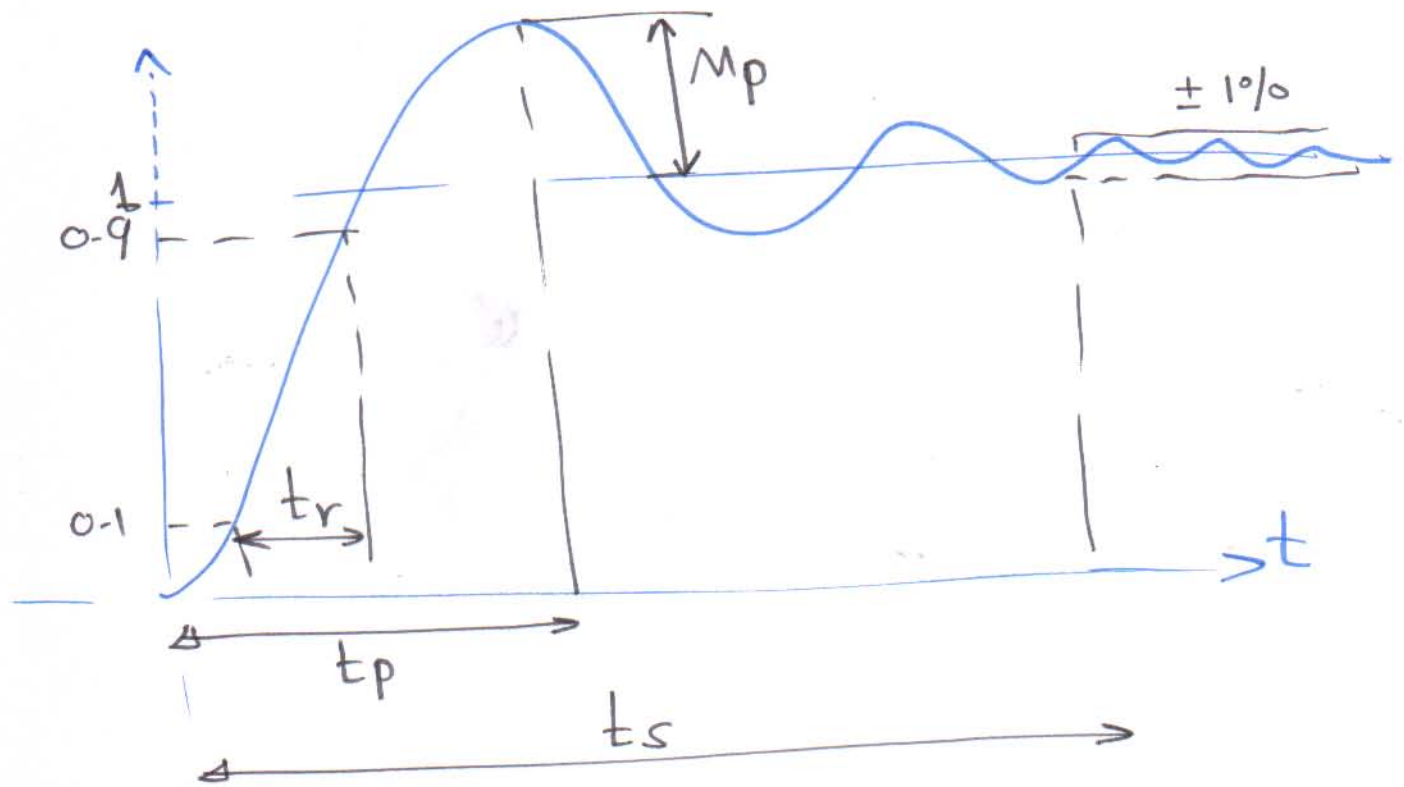


$\zeta > 1 \Rightarrow$ over damped



Time domain specification

for second-order system, step input, all the curves rise in roughly the same time, if we consider the curve for $\zeta = 0.5$ to be an average



$$\bullet t_r \approx \frac{1.8}{\omega_n}$$

$$\bullet t_p = \frac{\pi}{\omega_d}$$

$$\bullet M_p = e^{-\pi \zeta / \sqrt{1-\zeta^2}}$$

$$0 < \zeta < 1$$

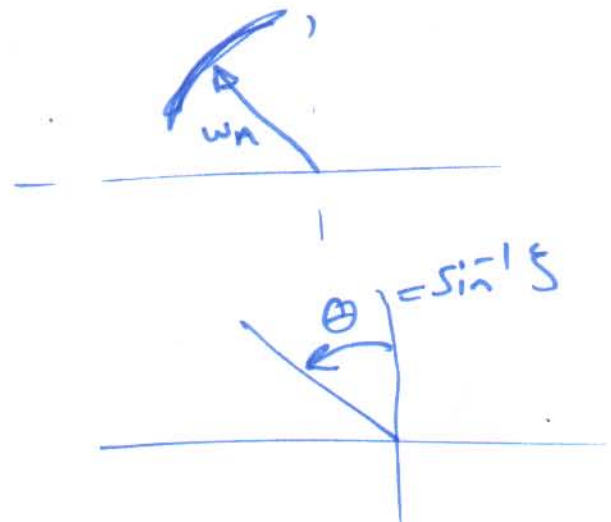
$$\bullet t_s = \frac{4.6}{\sigma} = \frac{4.6}{\zeta \omega_n}$$

Design point

$$\bullet \omega_n \geq \frac{1.8}{t_r}$$

$$\bullet \zeta \geq \zeta \text{ from } M_p$$

$$\bullet \sigma \geq \frac{4.6}{t_s} \rightarrow \zeta \leftarrow$$



(Ex)

Find the allowable regions in the s-plane for the poles of a transfer function if the system response requirement are $t_r \leq 0.6$, $M_p \leq 10\%$ and $t_s \leq 3$

(Sol.)

$$\therefore t_r = \frac{1.8}{\omega_n}$$

$$\therefore \frac{1.8}{\omega_n} \leq 0.6 \Rightarrow \omega_n \geq 3 \text{ rad/sec}$$

$$-\pi\xi/\sqrt{1-\xi^2}$$

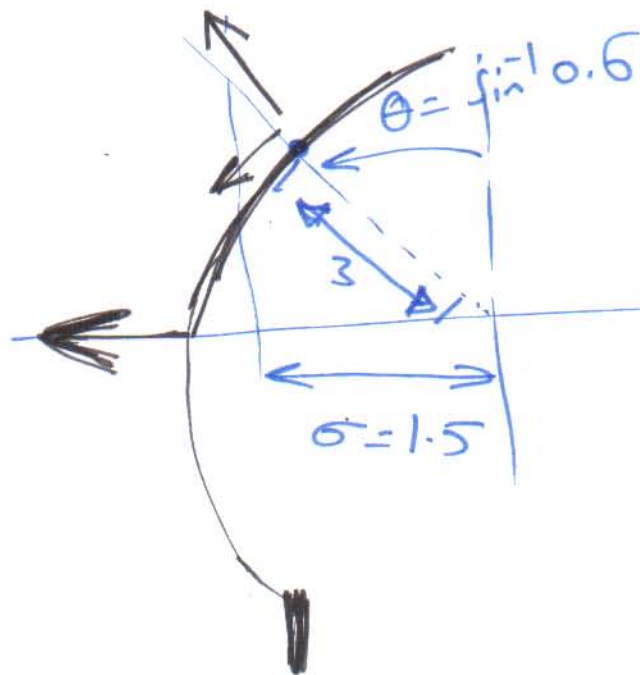
$$\therefore M_p = e$$

$$\therefore \xi \geq 0.6$$

$$\therefore t_s = \frac{4.6}{\sigma}$$

$$\frac{4.6}{\sigma} \leq 3$$

$$\therefore \sigma \geq 1.5$$



Prob.

Consider the system shown below

Assume that $\xi = 0.8$

$$\omega_n = 12 \text{ rad/sec}$$

Calculate

- delay time
- rise time
- overshoot mp
- settling time

Ex

$$T(s) = \frac{100}{s^2 + s + 100}$$

Find ω_n , ξ , ω_d

Sol.

$$\omega_n^2 = 100 \Rightarrow \omega_n = 10$$

$$2\xi\omega_n = 1 \Rightarrow \xi = \frac{1}{20} = 0.05$$

$$\omega_d = \omega_n \sqrt{1 - \xi^2} = 10 \sqrt{1 - (0.05)^2}$$

Prob.

$$T(s) = \frac{3s + 49}{s^2 + 3s + 49}$$

Prob.

$$T(s) = \frac{s^2 + 20}{s^2 + 2s + 20}$$

Find

$\omega_n, \zeta, \omega_d, t_p, t_s, M_p, t_r$