

Statistics

| Symmetry and Skewness (التناظر والانحراف)

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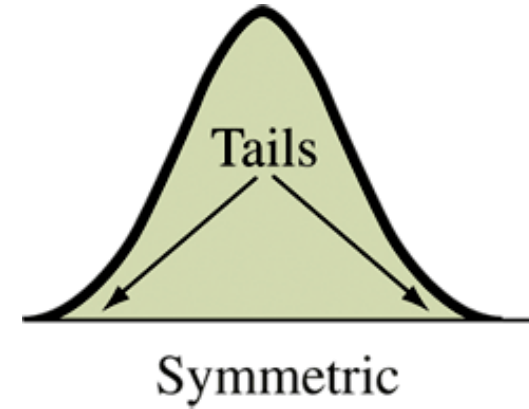
<https://youtube.com/drmelhosseini>

| Agenda

- Symmetric Distribution (Normal - Bell Shaped – Gaussian)
- What Is Skewness?
- Positive Skew (Right Skew)
- Negative Skew (Left Skew)
- Why the Shape is Important?
- How to Quantify Skewness?
- Examples - Codes

| Symmetric Distribution

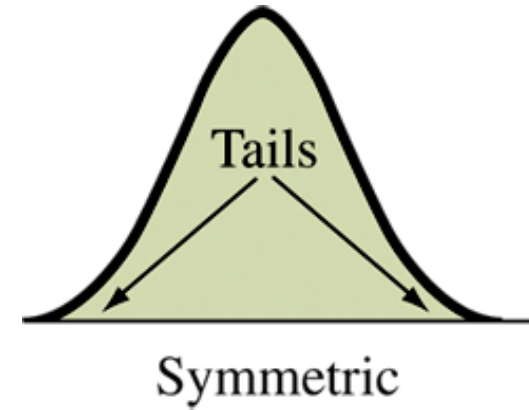
- The left and right sides **mirror** each other.
- Typically, the **mean = median = mode**.



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- Example: A perfectly normal (bell-shaped) distribution of standardized **test scores** (under an **ideal scenario**) or measurement errors in a well-controlled experiment.

| Symmetric Distribution

- The left and right sides mirror each other.
- Typically, the mean = median = mode.



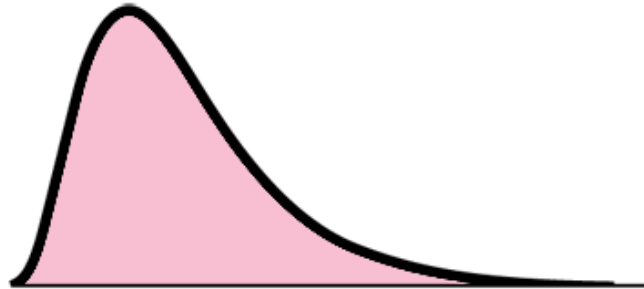
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- If you measure the **heights of adult males** in a homogeneous population, you might get a fairly symmetric (normal-like) distribution centered around a mean (e.g., 175 cm) and the **distribution tails decreasing at about the same rate in both directions**.

| What Is Skewness?

- Skewness is a **measure of asymmetry** in a distribution.
 - When a distribution is **symmetric**, the left side of its histogram (or curve) mirrors the right side.
 - When data “**skew**” to one side, one tail of the distribution is longer or fatter than the other.
- Formally, skewness can be **quantified** (e.g., using **Pearson’s** or **Fisher’s** measure of skewness)

| Types of Skewness

Positive Skew (Right Skew)

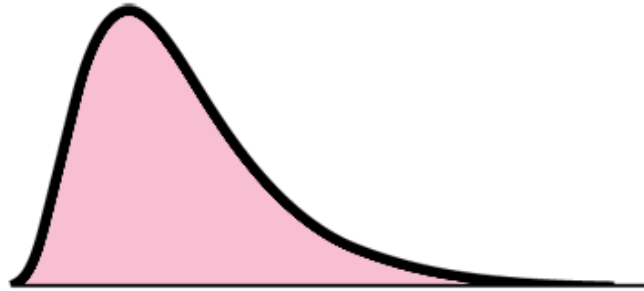


Skewed to the right

- The **right tail** of the distribution is **longer** (or fatter) than the left tail.
 - Typically, the **mean > median > mode**.
-
- Example: Income distribution often has a long right tail—most people earn below or around an average range, but a small number of very high incomes stretch out the tail on the right side.

| Types of Skewness

Positive Skew (Right Skew)



Skewed to the right

- The right tail of the distribution is longer (or fatter) than the left tail.
 - Typically, the mean $>$ median $>$ mode.
-
- Consider the distribution of **time to complete a new task** (e.g., an assembly line step). Some workers might complete it quickly (left side of the distribution), but a **few may take a significantly longer time** (right tail). This pulls the mean to the right.

| Types of Skewness

Negative Skew (Left Skew)



Skewed to the left

- The left tail of the distribution is longer (or fatter) than the right tail.
 - Typically, the **mean < median < mode**.
-
- Example: **Exam scores in an easy test** scenario often have a longer left tail: most students score very high, and a few lower scorers stretch out the tail on the left side..

| Types of Skewness

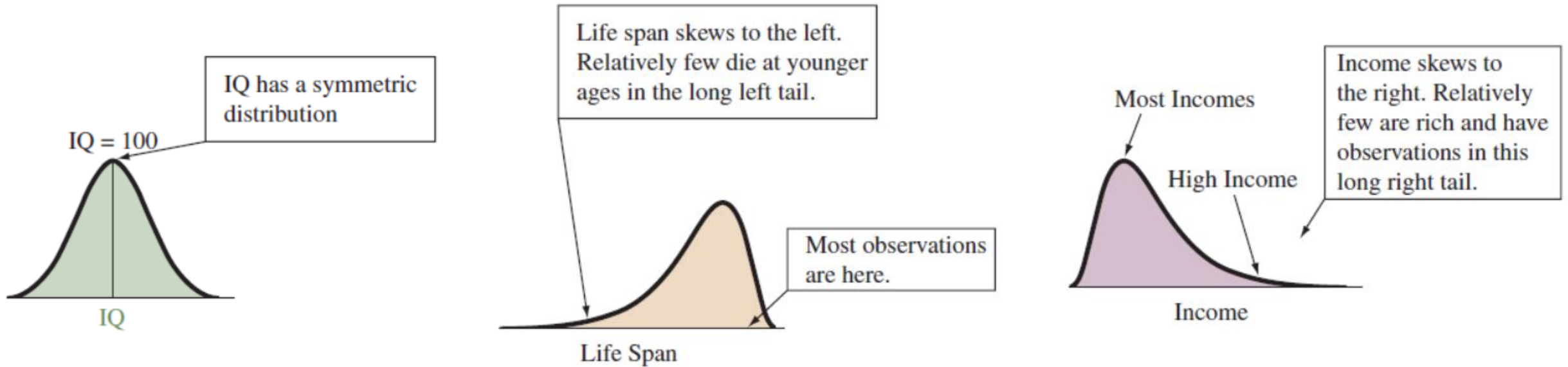
Negative Skew (Left Skew)



Skewed to the left

- The **left tail** of the distribution is **longer** (or fatter) than the right tail.
 - Typically, the **mean < median < mode**.
-
- Consider a **reading test for native speakers** in their own language. Most participants might achieve high scores (right side of the distribution), while just a small group may achieve much lower scores (left tail).

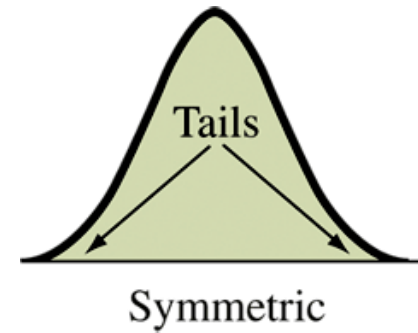
| To conclude



with small data sets, the shape of the distribution might not be so obvious

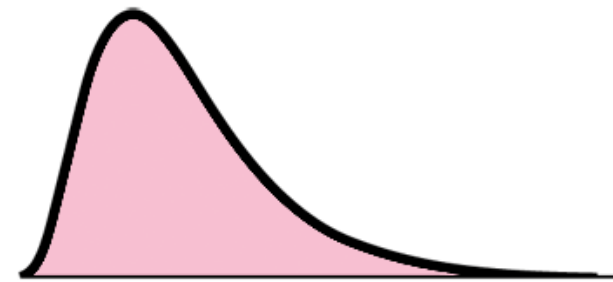
| To conclude

Symmetric Distributions: if both left and right sides of the histogram are mirror images of each other.



Skewed to the left

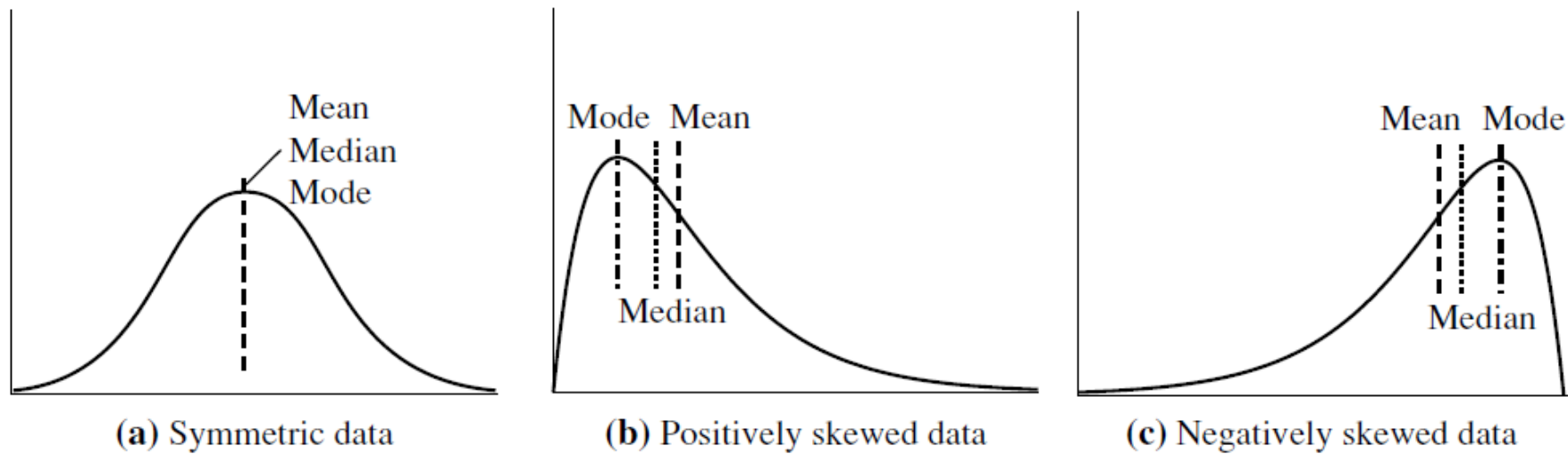
A distribution is **skewed to the left** if the left tail is longer than the right tail.



Skewed to the right

A distribution is **skewed to the right** if the right tail is longer than the left tail.

| To conclude



Mean, median, and mode of symmetric versus positively and negatively skewed data.

| Why the Shape is Important?

- In a **symmetric distribution**, the mean, median, and mode often **coincide** (or are very close). Therefore, using the **mean** is usually a **good representation** of the central tendency.
- In a skewed distribution, the mean, median, and mode can be far apart. Relying solely on the **mean might be misleading** because it can be dragged in the direction of the skew (towards the long tail). In such cases, the median may be a better indicator of the typical value.

| Why the Shape is Important?

- Many **statistical tests** assume **normality** (a symmetric, bell-shaped distribution). If data are highly skewed, these assumptions may not hold, and results (p-values, confidence intervals) could be invalid or misleading.
- Understanding the shape helps in deciding whether **data transformation** (e.g., taking logarithms) or nonparametric methods would be more appropriate.

| Why the Shape is Important?

- Skewness can hint at underlying phenomena—such as natural lower or upper bounds, outliers, or a long “tail” in one direction.
- For instance, in income distribution, it is common to have a few very high earners on the right-hand side (a right-skew), indicating that most people earn around a certain range, while a small number earn substantially more.

| How to Quantify Skewness

- Statisticians use different formulas (or coefficients) to measure the degree and direction of asymmetry (skewness) in a distribution. Below are the most common methods and interpretations:
- Pearson's Skewness Coefficients
 - Pearson's First Coefficient of Skewness
 - Pearson's Second Coefficient of Skewness
- Fisher-Pearson (Moment) Coefficient of Skewness

| How to Quantify Skewness

- Pearson's First Coefficient of Skewness

$$S_1 = \frac{\bar{X} - mode}{\sigma}$$

- $\bar{X}$: Mean
- σ : Standard Deviation
- Pearson's First Coefficient is used when the mode can be reliably identified.

| How to Quantify Skewness

- Pearson's Second Coefficient of Skewness

$$S_2 = \frac{3 \times (\bar{X} - \text{Median})}{\sigma}$$

- $\bar{X}$: Mean
- σ : Standard Deviation
- Pearson's Second Coefficient is often preferred when the mode is unclear or difficult to determine.

| How to Quantify Skewness

Interpreting Skewness Values

- There are no absolute cutoffs, but a common rule of thumb is:
- Skewness between -0.5 and 0.5 : The distribution is roughly symmetric.
- Skewness between -1 and -0.5 or between 0.5 and 1 : Moderate skew.
- Skewness <-1 or Skewness >1 : High (severe) skew.

| How to Quantify Skewness

Interpreting Skewness Values

- If $(\bar{X} - mode)$ is positive $s_1 > 0 \rightarrow$ Right Skew
- If $(\bar{X} - mode)$ is Negative $s_1 < 0 \rightarrow$ Left Skew

- If $(\bar{X} - Median)$ is positive $s_1 > 0 \rightarrow$ Right Skew
- If $(\bar{X} - Median)$ is Negative $s_1 < 0 \rightarrow$ Left Skew

| How to Quantify Skewness

Fisher-Pearson (Moment) Coefficient of Skewness

- This is the most commonly reported measure in statistical software (e.g., `scipy.stats.skew` in Python, or `skewness()` in R). It is based on the third central moment

$$g_1 = \frac{n}{(n-1)(n-2)} \sum_{i=1}^n \left(\frac{x_i - \bar{x}}{s} \right)^3$$

- x_i : is each data point
- $\bar{x}$: is the sample mean
- s : sample standard deviation
- n : is the sample size

| How to Quantify Skewness

Fisher-Pearson (Moment) Coefficient of Skewness

$$g_1 = \frac{n}{(n-1)(n-2)} \sum_{i=1}^n \left(\frac{x_i - \bar{x}}{s} \right)^3$$

- $\frac{n}{(n-1)(n-2)}$ serves as a bias correction for small sample sizes
- $g_1 \cong 0 \rightarrow$ The distribution is (approximately) symmetric.
- $g_1 > 0 \rightarrow$ The distribution is positively (right) skewed (long right tail).
- $g_1 < 0 \rightarrow$ The distribution is negatively (left) skewed (long left tail).

| Key Points When Measuring Skewness

- Extreme values (outliers) can strongly influence skewness coefficients.
- With small samples, skewness estimates may not reflect the true underlying distribution accurately. Bias corrections (like in the Fisher-Pearson method) help mitigate this.
- Use Pearson's First Coefficient when the mode is known and distinct.

| Key Points When Measuring Skewness

- Use Pearson's First Coefficient when the mode is known and distinct.
- Use Pearson's Second Coefficient (median-based) or the Fisher-Pearson coefficient when the mode is unknown or less meaningful.
- In cases of severe skewness, transformations (e.g., log or square-root) can help normalize data before applying parametric statistical tests that assume (near) normality.

| Simple Example

- 9 data points (already sorted for convenience):
{1, 2, 2, 3, 4, 8, 9, 12, 15}
- We will compute:
 - Mean
 - Median
 - Mode
 - Standard Deviation (Sample)
 - Pearson's Skewness Coefficients (First & Second)
 - Fisher-Pearson (Moment) Coefficient (Optional, if you want to see a more advanced measure)

| Simple Example

- Mean = $\bar{x} = \frac{1+2+2+3+4+8+9+12+15}{9} = \frac{56}{9} = 6.22$
- Median: The middle (5th) value is 4. Median = 4
- Mode = 2
- Standard Deviation (Sample) $s = 4.996$
- Pearson's First Coefficient $s_1 = \frac{\bar{x} - mode}{s} = \frac{6.22 - 2}{4.996} = 0.84$

| Simple Example

- Mean = $\bar{x} = \frac{1+2+2+3+4+8+9+12+15}{9} = \frac{56}{9} = 6.22$
- Median: The middle (5th) value is 4. Median = 4
- Mode = 2
- Standard Deviation (Sample) $s = 4.996$
- Pearson's Skewness Coefficients (First & Second) S_2
$$= \frac{3 \times (\bar{X} - \text{Median})}{s} = \frac{3 \times (6.22 - 4)}{4.996} = 1.33$$

| Simple Example

- Mean = $\bar{x} = \frac{1+2+2+3+4+8+9+12+15}{9} = \frac{56}{9} = 6.22$
- Median: The middle (5th) value is 4. Median = 4
- Mode = 2
- Standard Deviation (Sample) $s = 4.996$
- Fisher-Pearson (Moment) Coefficient (Optional, if you want to see a more advanced measure) $g_1 = \frac{n}{(n-1)(n-2)} \sum_{i=1}^n \left(\frac{x_i - \bar{x}}{s} \right)^3$
- $g_1 = +0.72$ (moderately positive skew)

| Simple Example

- Interpretation:
- From these calculations:
 - Pearson's First Skewness $S1 \approx 0.84$
 - Pearson's Second Skewness $S2 \approx 1.33$
 - Fisher-Pearson (Moment) Coefficient $g1 \approx 0.72$
- All are positive values, confirming the data are right-skewed (positively skewed). This aligns with the pattern that a few larger values at the high end (9, 12, 15) pull the mean to the right, making it notably higher than the median and mode.

| Heavily Left-Skewed Distribution Example

- We generate 100 data points from a Beta(20, 2) distribution, which is known to be heavily left (negatively) skewed.
- Statistical Measures
 - Mean
 - Median
 - Sample Standard Deviation
 - Fisher-Pearson Skewness
(stats.skewstats.skew)
- Interpretation
 - If skewness < 0 , the tail is to the left → negatively skewed.
 - The histogram visually confirms the shape: values cluster near 1 with a long tail toward 0.

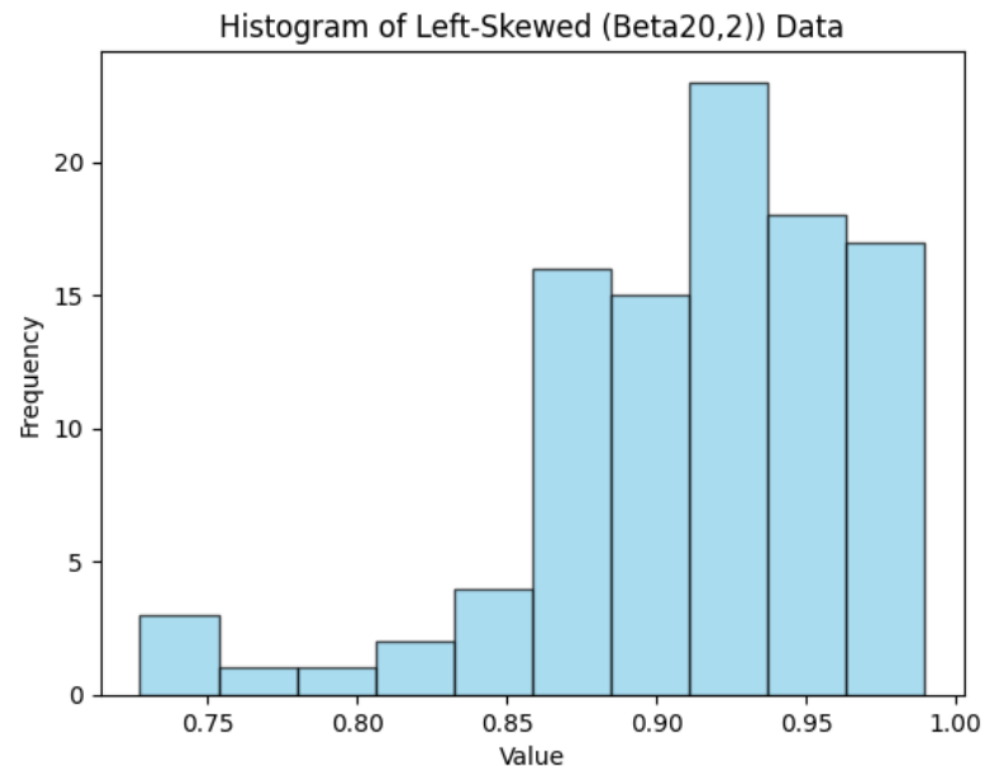
| Heavily Left-Skewed Distribution Example

- Most values near 1, with a long tail stretching toward 0
- The mean is typically slightly less than the median, reflecting the left-side tail pulling the mean downward.

```
mean_value = np.mean(data)
median_value = np.median(data)
std_value = np.std(data, ddof=1)
skew_value = stats.skew(data, bias=False)
```

----- Basic Statistics -----

```
Mean: 0.9116
Median: 0.9233
Std: 0.0550
Skew: -1.2293
```



| References

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- Agresti, A. and Franklin, C., 2007. The art and science of learning from data. Upper Saddle River, New Jersey, 88.
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